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(71) Applicant (for all designated States except US): TOY-OTA JIDOSHA KABUSHIKI KAISHA [JP/JP]; 1, Toyota-cho, Toyota-shi, Aichi 4718571 (JP).

(72) Inventors; and

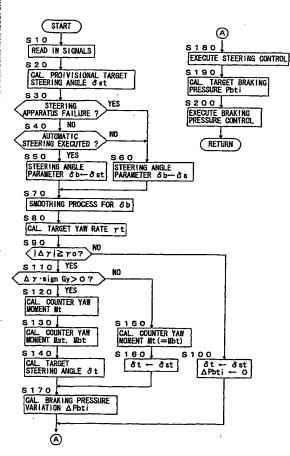
(75) Inventors/Applicants (for US only): SUZUMURA,

Masato [JP/JP]; C/o Toyota Jidosha Kabushiki Kaisha, 1, Toyota-cho, Toyota-shi, Aichi 4718571 (JP). ASANO, Kenji [JP/JP]; C/o Toyota Jidosha Kabushiki Kaisha, 1, Toyota-cho, Toyota-shi, Aichi 4718571 (JP).

- (74) Agent: AKASHI, Masaki; 5f, YH Bldg., 6-8, Shinkawa 2-chome, Chuo-ku, Tokyo 1040033 (JP).
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(54) Title: VEHICLE STABILITY CONTROL DEVICE



(57) Abstract: A novel vehicle stability control device through steering wheels independently of the driver's handling operation is provided, in which a suitable steering angle parameter in determining a target value for a turning state parameter is selected. The control device calculates a provisional target steering angle for wheels based upon an amount of an operation of a driver and a predetermined steering characteristic; a target value for the turning state parameter; and a target steering angle for wheels for reducing a magnitude of a deviation of the actual turning state parameter from its target value when the magnitude of the deviation is at a reference value or above, and thereby controlling a steering angle based upon the target steering angle, the target value of the turning state parameter is calculated based upon the provisional target steering angle.

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